**Touch Protocol - Guided**

*Note: This module is intended to be used with two experimenters. Experimenter A will be interacting with the robot and child. Experimenter B will be operating Choreographe, preferably out of sight or in a way that hides that Experimenter B is controlling the robot. The NAO’s ear LEDs turn blue when the program has loaded, so that Experimenter A knows when they are able to proceed. Our robot is named Russell, and we refer to him as such throughout the study. Do not keep the robot in the crouching position for an extended period of time, as it will cause the robot’s joints to overheat.*

**Researcher A**: Russell needs to have a little rest now, so I’m going to let him sleep. Do you want to say good night to Russell?

* *If child protests*: He’s really tired, and we need to recharge him.

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| **Experimenter A** |
| 1. Tap head sensory when light is blue to make Russell “shut down” |

**Researcher A:** While he’s asleep, can you help me give Russell a quick check-up? I think you’ll be really good at it. You can help me by touching different parts of his body when I say their name. So if I ask you to touch his knees, you’ll just touch them like this. *[Demonstrate by gently touching the robot’s knees.]* Does that sound okay? It would really help me out.

*[Wait for participant to agree to participate.]*

Great. Can you touch his hands for me? *[Wait for participant to gently touch the robot’s hands. Provide corrective feedback, guidance, or demonstrate if necessary at each step.]*

Good job. Now can you touch his mouth? *[Wait.]*

Wonderful. Can you touch his shoulders? *[Wait.]*

Great. Can you touch his forehead for me? *[Wait.]*

Brilliant. And last, can you touch his elbows for me? *[Wait.]*

Great job, thank you! Everything’s working perfectly. You did great!